

Beliefs and Defaults

Material used

- Halpern: Reasoning about Uncertainty, Chapter 8

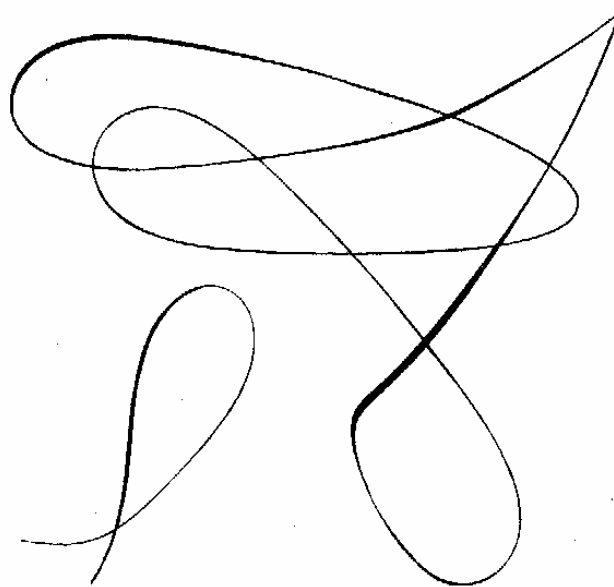
- 1 Motivating examples
- 2 Beliefs
- 3 Characterizing default reasoning
- 4 Semantics for defaults
- 5 Beyond system **P**

0 Introduction

- Default reasoning involves leaping to conclusions. It is a case of presumptive reasoning
- Counterfactual reasoning involves reaching conclusions with assumptions that may be counter to facts.
- Both cases of reasoning are defeasible and both involve uncertainty
- The earlier means to capture uncertainty (possibility, ranking functions and various measures for plausibility) can be used to define particular kinds of presumptive reasoning.

1 Some examples

Some examples should convince you that plausible or presumptive reasoning is not completely arbitrary but regulated by general principles.



- If birds typically fly, and if birds typically sing, then birds typically fly and sing

$$\{B \triangleright F, B \triangleright S\} \vdash B \triangleright (F \wedge S)$$

- If red birds typically fly and if non-red birds typically fly, then birds typically fly (*reasoning by cases*)

$$\{(R \wedge B) \triangleright F, (\neg R \wedge B) \triangleright F\} \vdash B \triangleright F$$

- * If birds typically fly, then handicapped birds typically fly (*monotonicity*)

not valid: $\{B > F\} \not\vdash (H \wedge B) > F$

- * If birds typically fly, then penguins typically fly

not valid: $\{B > F, P \Rightarrow B\} \not\vdash P > F$

- If birds typically fly and birds typically have wings, then birds that have wings typically fly (*cautious monotonicity*)

$\{B > F, B > W\} \vdash (B \wedge W) > F$

Defeasible inferences

- If birds typically can fly and Fido is a bird, then Fido can fly (*defeasible modus ponens*)

$$\{B \triangleright F, B\} \mid \sim F$$

- *If birds typically can fly and Fido is a bird, but it cannot fly (it's a penguin), then Fido can fly

not valid: $\{B \triangleright F, B, \neg F\} \mid \sim F$; valid $\{B \triangleright F, B, \neg F\} \mid \sim \neg F$

[This shows that $\mid \sim$ is nonmonotonic]

- ?If students are typically adults and adults typically are car drivers, then students typically are car drivers (*transitivity*)

? $\{S \triangleright A, A \triangleright C\} \mid \sim S \triangleright C$

2 Belief

A general model of beliefs uses *filters*.

Definition 1: Given a set of possible worlds W , a **filter** F is a nonempty set of subset of W that

1. is closed under supersets: $U \subseteq V \ \& \ U \in F \Rightarrow V \in F$
2. is closed under intersection: $U, V \in F \Rightarrow U \cap V \in F$
3. does not contain the empty set

The general conception of a filter does not give any insight where beliefs are coming from. It's a descriptive modelling instrument only.

If $W^0 \subseteq W$ represents the agent's belief then we call (W, W^0) a *belief space*.

Definition 2: Let $\Sigma = (W, W^0)$ be a belief space.

- $\Sigma \Vdash \text{Bel}_x(U)$ iff $W^0 \subseteq U$ (x believes U)

Fact 1: The events that are believed with regard to a fixed belief space Σ are filters, i.e.:

- $\Sigma \Vdash \text{Bel}_x(U) \ \& \ U \subseteq V \Rightarrow \Sigma \Vdash \text{Bel}_x(V)$
- $\Sigma \Vdash \text{Bel}_x(U) \ \& \ \Sigma \Vdash \text{Bel}_x(V) \Rightarrow \Sigma \Vdash \text{Bel}_x(U \cap V)$
- not $\Sigma \Vdash \text{Bel}_x(\emptyset)$

Let (W, \mathcal{F}, μ) be a probability space.

Fact 2: The events with probability 1 form a filter, i.e.

- $\mu(U)=1 \ \& \ U \subseteq V \Rightarrow \mu(V)=1$
- $\mu(U)=1 \ \& \ \mu(V)=1 \Rightarrow \mu(U \cap V)=1$
- $\mu(\emptyset) \neq 1$

In the following we investigate a more insightful model that makes use of plausibility spaces (generalizing probabilities)

Plausibility spaces

- A plausibility measure is a generalization of all the approaches to uncertainty treated in the first part (probability, inner/outer measure, possibility, ranking functions)
- Formally, a plausibility space is a tuple $S = (W, \mathcal{F}, Pl)$, where \mathcal{F} is an algebra over W and $Pl: \mathcal{F} \rightarrow D$ where D is a set of plausibility values partially ordered by a relation $<_D$. The relation $<_D$ has a minimal element \perp and a maximal element \top .
- **P11.** $Pl(\emptyset) = \perp$
P12. $Pl(W) = \top$
P13. $U \subseteq V \Rightarrow Pl(U) \leq Pl(V)$

Plausibility spaces and beliefs

With regard to a plausibility space $S = (W, \mathcal{F}, Pl)$ it is possible to give the most general definition for beliefs.

Definition 3: Given a plausibility space $S = (W, \mathcal{F}, Pl)$, say that an agent *believes* $U \in \mathcal{F}$ iff $Pl(U) > Pl(\neg U)$

Fact 3: This definition satisfies closure under supersets, i.e.:
 $U \subseteq V \ \& \ Pl(U) > Pl(\neg U) \Rightarrow Pl(V) > Pl(\neg V)$

Proof: exercise

Unfortunately, this definition does not satisfy closure under conjunction in the general case:

$$Pl(U_1) > Pl(\neg U_1) \ \& \ Pl(U_2) > Pl(\neg U_2) \Rightarrow Pl(U_1 \cap U_2) > Pl(\neg(U_1 \cap U_2))$$

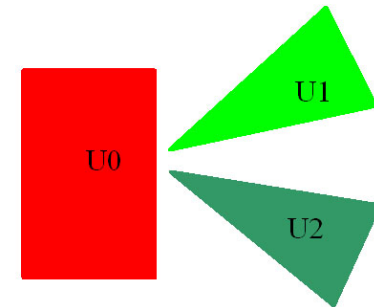
The condition P14

However, we can stipulate this as an extra condition:

$$Pl(U_1) > Pl(\neg U_1) \ \& \ Pl(U_2) > Pl(\neg U_2) \Rightarrow Pl(U_1 \cap U_2) > Pl(\neg(U_1 \cap U_2))$$

In order to deal with conditioned plausibilities a somewhat stronger condition is stipulated:

P14. If U_0 , U_1 , and U_2 are pairwise disjoint sets, then $Pl(U_0 \cup U_1) > Pl(U_2)$ & $Pl(U_0 \cup U_2) > Pl(U_1)$
 $\Rightarrow Pl(U_0) > Pl(U_1 \cup U_2)$



In words, if $U_0 \cup U_1$ is more plausible than U_2 and if $U_0 \cup U_2$ is more plausible than U_1 , then U_0 by itself is already more plausible than $U_1 \cup U_2$.

Remark: P14 is necessary and sufficient to guarantee that (conditional) beliefs are closed under conjunction.

Ranking functions and the condition P14

Fact 4: The condition P14 is generally satisfied for possibility measures (and ranking functions).

In order to prove

$$Pl(U_0 \cup U_1) > Pl(U_2) \ \& \ Pl(U_0 \cup U_2) > Pl(U_1) \Rightarrow Pl(U_0) > Pl(U_1 \cup U_2)$$

assume that $Pl(X \cup Y) = \max(Pl(X), Pl(Y))$

Case 1: $Pl(U_0) \geq Pl(U_1)$, then the premise reduces to $Pl(U_0) > Pl(U_2) \ \& \ Pl(U_0) > Pl(U_1)$ and the consequence part follows obviously.

Case 2.1: $Pl(U_0) < Pl(U_1)$, $Pl(U_0) < Pl(U_2)$, then the premise reduces to $Pl(U_1) > Pl(U_2) \ \& \ Pl(U_2) > Pl(U_1)$ and the consequence is trivially true.

Case 2.2: $Pl(U_0) < Pl(U_1)$, $Pl(U_0) \geq Pl(U_2)$, then the premise reduces to $Pl(U_1) > Pl(U_2) \ \& \ Pl(U_0) > Pl(U_1)$ and the consequence is true.

Consequence: *An agent believes U according to definition 3 gives a filter if the plausibility function Pl is based on a possibility measure!*

3 Characterizing default reasoning

Giving a set At of primitive (atomic) propositions, the language $\mathcal{L}^{\text{defaults}}(At)$ consists of all formulas of the form $\phi > \psi$ where ϕ and ψ are propositional formulas over At .

The formula $\phi > \psi$ can be read in various ways, depending on the application:

- If ϕ is the case then typically ψ is the case
- If ϕ the normally ψ
- If ϕ then by default ψ
- If ϕ then ψ is very likely
- If ϕ were the case then ψ would be true.

Core properties

Though there is some disagreement in the literature as to what properties $>$ should have, there seems to be a consensus on the following set of six core properties, which make up the axiom system **P**:

- LLE (left logical equivalence): If $\phi \leftrightarrow \phi'$ is a propositional tautology, then from $\phi > \psi$ infer $\phi' > \psi$
- RW (right weakening): If $\psi \rightarrow \psi'$ is a propositional tautology, then from $\phi > \psi$ infer $\phi > \psi'$
- REF (reflexivity): $\phi > \phi$
- AND: From $\phi > \psi_1$ and $\phi > \psi_2$ infer $\phi > \psi_1 \wedge \psi_2$
- OR: From $\phi_1 > \psi$ and $\phi_2 > \psi$ infer $\phi_1 \vee \phi_2 > \psi$
- CM (cautious monotonicity): From $\phi > \psi_1$ and $\phi > \psi_2$ infer $\phi \wedge \psi_2 > \psi_1$

Definition 4:

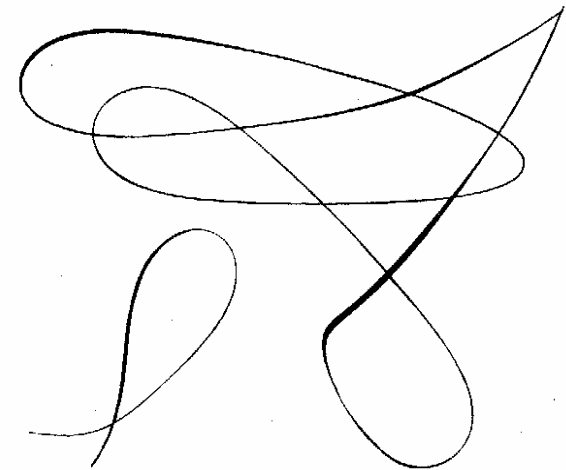
Let Σ be a finite set of formulas in $\mathcal{L}^{\text{defaults}}(At)$. Then write $\Sigma \mid_{-\mathbf{P}} \phi > \psi$ iff $\phi > \psi$ can be deduced from Σ using the rules and axioms of \mathbf{P}

Example: Prove that $\{B > E, B > W, B > F\} \mid_{-\mathbf{P}} B \wedge (W \vee E) > F$

1. Take $\{B > E, B > W, B > F\}$ as premises
2. from 1 infer $(B \wedge W) > F$ (CM)
3. from 1 infer $(B \wedge E) > F$ (CM)
4. from 2 & 3 infer $(B \wedge E) \vee (B \wedge W) > F$ (OR)
5. $(B \wedge E) \vee (B \wedge W) \leftrightarrow B \wedge (W \vee E)$ is a propositional tautology
6. from 4 & 5 infer $B \wedge (W \vee E) > F$ (LLE)

4 Semantics for defaults

There have been many attempts to give semantics to formulas in $\mathcal{L}^{\text{defaults}}(At)$. The surprising thing is how many of them have ended up being characterized by the basic axiom system **P**. A semantics based on plausibility measures helps to explain why **P** characterizes so many different approaches. The property P14 is essential in this connection



Probabilistic semantics

Let $M = (W, \mu, \pi)$ be a simple probability structure, i.e. W is a set of possible worlds, μ a probability function on the subsets of W , and π is interpretation function for our language $\mathcal{L}^{\text{defaults}}(At)$. $\pi(p_i)$ assigns subsets of W to the atoms $p_i \in At$.

Definition 5: Interpretation of $\mathcal{L}^{\text{defaults}}(At)$.

$$\llbracket p_i \rrbracket = \pi(p_i) \text{ for } p_i \in At.$$

$$\llbracket \neg\phi \rrbracket = \neg \llbracket \phi \rrbracket$$

$$\llbracket \phi \wedge \psi \rrbracket = \llbracket \phi \rrbracket \cap \llbracket \psi \rrbracket$$

$$\llbracket \phi \vee \psi \rrbracket = \llbracket \phi \rrbracket \cup \llbracket \psi \rrbracket$$

Remark: all interpretations $\llbracket . \rrbracket$ are with regard to the structure M !

$$\text{(CP)} \quad M \models \phi > \psi \text{ iff } \mu(\llbracket \psi \rrbracket \mid \llbracket \phi \rrbracket) = 1$$

Probabilistic semantics cont.

- It is not difficult to show that this definition of defaults in (conditional) probability structures satisfies all the axioms and rules of axiom system **P**.
- In fact, **P** can be viewed as a sound and complete axiomatization of default reasoning for the language $\mathcal{L}^{\text{defaults}}(At)$. In order to make that precise...

Definition 6: $\Sigma \models \phi > \psi$ iff for all structures M for which each sentences of Σ is true, the default $\phi > \psi$ also is true

Fact 5: $\Sigma \vdash_{\mathbf{P}} \phi > \psi$ iff $\Sigma \models \phi > \psi$

- Is the intuitive interpretation of the last clause (CP) of Definition 5 really plausible?

Replace the condition (CP) in the definition 5 by the following definition making use of a fix, very small number $\varepsilon > 0$.

$$(\varepsilon\text{-CP}) \quad M \models \phi > \psi \text{ iff } \mu(\llbracket \psi \rrbracket \mid \llbracket \phi \rrbracket) > 1 - \varepsilon$$

- It can be shown this definition satisfies LLE, RW, REF but not AND, CM, and OR (see exercise)
- However, if we consider sequences of probability functions (μ_1, μ_2, \dots) then the corresponding definition conforms to **P**:

$$(\infty\text{-CP}) \quad M \models \phi > \psi \text{ iff } \lim_{k \rightarrow \infty} \mu_k(\llbracket \psi \rrbracket \mid \llbracket \phi \rrbracket) = 1$$

- It is not so clear where the sequence of probabilities is coming from

Using possibility measures

(Poss) $M \models \phi > \psi$ iff $\text{Poss}(\llbracket \phi \rrbracket) = 0$ or
 $\text{Poss}(\llbracket \phi \wedge \psi \rrbracket) > \text{Poss}(\llbracket \phi \wedge \neg \psi \rrbracket)$

Remember the definition of possibility measures:

Poss1. $\text{Poss}(\emptyset) = 0$

Poss2. $\text{Poss}(W) = 1$

Poss3. $\text{Poss}(U \cup V) = \max(\text{Poss}(U), \text{Poss}(V))$

Theorem: The definition (Poss) of the truth-conditions for $\phi > \psi$ satisfies all the axioms and rules of axiom system **P**. Moreover, **P** is a complete characterization of the corresponding semantics: $\Sigma \vdash_{\mathbf{P}} \phi > \psi$ iff $\Sigma \models \phi > \psi$.

(for the proof see Halpern, p. 299)

5 Beyond system P

- The system P has been viewed as characterizing the “conservative core” of default reasoning.
- For practical reasons (modeling of presumptive reasoning) it is useful to add a “nonmonotonic periphery” in order to deal with defeasible reasoning.
- One example is *defeasible modus ponens*, another is exceptional subclass inheritance:
 $\{penguin \Rightarrow bird, bird \triangleright winged\} \mid \sim penguin \triangleright winged$

(Although penguins are an exceptional subclass of birds (property *fly!*) , it seems reasonable for them to still inherit the property of having wings from birds)

The semantics of the periphery

Instead of the standard definition of entailment (semantic consequence) repeated here a new definition 7 is used that makes use of preferred structures

Definition 6: $\Sigma \models \phi > \psi$ iff for **all** structures M for which each sentences of Σ is true, the default $\phi > \psi$ also is true

Definition 7: $\Sigma \models \phi > \psi$ iff for all **preferred** structures M for which each sentences of Σ is true, the default $\phi > \psi$ also is true

Example for preferred structures: looking for probability distributions that maximize the entropy (see Halpern p. 309)