The Necker-Zeno Model

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Mathematical Approaches in Psychology Generalized Quantum Theory

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Some Remarks

• psychology is different from neuroscience

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Mathematics serves the precise formulation of conceptual questions in terms of abstract structures (algebras, graphs, etc.).

Data processing includes the numerical quantification of observables, statistical analysis of measurement results, etc.

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Observational processes are interactions of an observing system O with an observed system S (state ψ , observables A, B, ...):

(i) weak interaction: no significant effect of O on S,

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- (ii) quantum case, $AB\psi \neq BA\psi$ non-commutative

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Physics:

- (i) classical case, $AB\psi = BA\psi$ commutative
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Psychology:

Almost every action of O entails a significant effect on S. Non-commutativity is the rule rather than the exception.

 \rightarrow generalized quantum theory details

Necker Cube Quantum Zeno Effect Necker-Zeno Model

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Bistable perception of ambiguous stimuli: the Necker cube



spontaneous switches between two possible 3–D representations at a time scale of some seconds

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Misra and Sudarshan (1977): Quantum Zeno Effect

• Two kinds of processes in an unstable two-state system:

"observation":
$$\sigma_3 = \left(\begin{array}{cc} 1 & 0 \\ 0 & -1 \end{array} \right)$$
 switching dynamics: $\sigma_1 = \left(\begin{array}{cc} 0 & 1 \\ 1 & 0 \end{array} \right)$

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• The switching dynamics is a continuous rotation according to

$$U(t) = e^{iHt} = \left(egin{array}{cc} \cos gt & i\sin gt \ i\sin gt & \cos gt \end{array}
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with $H = g\sigma_1$, and $t_o = 1/g$ characterizes the decay time of the system.

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 "Observation" process is a projection P₊ or P₋ onto one of the two eigenstates of σ₃.

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 System dynamics without observations: Probability that the system is in state |+⟩ at time t if it was in |+⟩ at t = 0:

 $w_1(t) = \cos^2(gt)$

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Successive observations at intervals ΔT: Probability that the system is in state |+⟩ at time t = N · ΔT if it was in |+⟩ at t = 0:

$$w_N(t) = (\cos^2(g\Delta T))^N$$

 $\approx \exp(-g^2\Delta T^2 \cdot N) = \exp(-\frac{\Delta T}{t_0^2}t)$

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 Effect of observations: stabilization of the system in its unstable states, "dwell time" increases from unperturbed t_o to an average time (T):

$$\left< T \right> \approx t_o^2 \, / \, \Delta T$$

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From Quantum Zeno to Necker-Zeno

 States |+⟩ and |-⟩ correspond to the cognitive states in the two possible representations of the Necker cube.

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From Quantum Zeno to Necker-Zeno

- States $|+\rangle$ and $|-\rangle$ correspond to the cognitive states in the two possible representations of the Necker cube.
- Two complementary processes:
 - (i) unperturbed switching dynamics with characteristic time t_0 ,
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- Two complementary processes:
 - (i) unperturbed switching dynamics with characteristic time t_0 ,
 - (ii) projection into a representation due to successive "updates" (ΔT).
- Associated cognitive time scales:

intrinsic update interval $\Delta T \approx$ 30 msec

(sequentialization of successive stimuli, wagon wheel illusion)

- $t_o \approx 300$ msec (time for a stimulus to become conscious, P300)
- $\langle {\it T} \rangle \approx$ 3 sec (average "dwell time" for bistable states / representations)

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Dwell Time Distribution Discontinuous Presentation

Observed Γ -distribution of dwell times T: $P(T) \propto T^b \exp(-\gamma T)$ Model so far has b = 0 (purely exponential decay of P(T)), refine with initial behavior due to effects of attention: (a) increasing ΔT , (b) decreasing t_o .

- solid lines: Γ -distribution with b = 2 and $t_0 = 300$ msec for $\Delta T = 70$ msec (highest maximum) and $\Delta T = 30$ msec - P(T) according to Necker-Zeno model with decreasing t_o for $\Delta T = 70$ msec (crosses) and $\Delta T = 30$ msec (squares)



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Dwell Time Distribution Discontinuous Presentation

Dwell times $\langle T \rangle$ for off-times $t_{\rm off} > 300$ msec



experimental values: crosses from Kornmeier and Bach (2004), squares from Orbach *et al.* (1966)

plotted curve according to the Necker-Zeno model for $\Delta \mathcal{T} \approx 70 \mbox{ msec}$

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Dwell Time Distribution Discontinuous Presentation

Reversal rates $1/\langle T angle$ for off-times $t_{ m off} <$ 300 msec



experimental values with error bars: from Kornmeier *et al.* (2007)

asterisks: best fit according to the Necker-Zeno model, yielding $\Delta T \approx 16$ msec and $t_0 \approx 210$ msec

squares: values for $\Delta T = 30$ msec and $t_0 = 300$ msec

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Background Temporal Bell Inequalitites

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• Question: Can mental events always be uniquely assigned to instances without temporal extension?

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- Bergson, James, Whitehead, etc., specious present, actual occasion, etc.: temporally extended events within which no further temporal localization (or segmentation) is possible. → temporal nonlocality

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- Violations of temporal Bell inequalities would indicate temporal nonlocality (but in quantum mechanics time and dynamics are commutative).
- In the Necker-Zeno model there are two kinds of non-commuting dynamics, so there is a chance to violate temporal Bell inequalities in bistable perception.

Background Temporal Bell Inequalitites

Sudarshan (1983)



... a mode of awareness in which "sensations, feelings, and insights are not neatly categorized into chains of thoughts, nor is there a step-by-step development of a logical-legal argument-to-conclusion. Instead, patterns appear, interweave, coexist; and sequencing is made inoperative. Conclusion, premises, feelings, and insights coexist in a manner defying temporal order."

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Background Temporal Bell Inequalitites

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Specify three different instances t₁, t₂, t₃ in a classical trajectory in which the state of the system at t_i is s(t_i) = {+1, −1}.



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• Any classical trajectory falls into one of $2^3 = 8$ possible classes: 111, 11-1, 1-11, -111, 1-1-1, -11-1, -1-11, -1-1-1.

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Specify three different instances t₁, t₂, t₃ in a classical trajectory in which the state of the system at t_i is s(t_i) = {+1, -1}.



- Any classical trajectory falls into one of 2³ = 8 possible classes: 111, 11-1, 1-11, -111, 1-1-1, -11-1, -1-11, -1-11.
- Define N⁻(t_i, t_j) as the number of cases with s(t_i) ≠ s(t_j), hence s(t_i)s(t_j) = −1, for each of the 8 possible trajectories.

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- Define N⁻(t_i, t_j) as the number of cases with s(t_i) ≠ s(t_j), hence s(t_i)s(t_j) = −1, for each of the 8 possible trajectories.
- For each trajectory, $N^-(t_1, t_3) \le N^-(t_1, t_2) + N^-(t_2, t_3)$. Normalize N to p, replace (t_i, t_j) by $(t_j - t_i)$:

 $p^-(t_3-t_1) \leq p^-(t_2-t_1) + p^-(t_3-t_2)$ (temporal Bell inequality)

Background Temporal Bell Inequalitites

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• In the Necker-Zeno model, the probability for state $|-\rangle$ at time t_2 under the condition of state $|+\rangle$ at time t_1 (and vice versa) is:

$$w_{+-}(t_1, t_2) = w_{-+}(t_2, t_1) = \sin^2 g(t_2 - t_1)$$

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• Then $p^{-}(t_1, t_2)$ for anti-correlated states at t_1 and t_2 is: $p^{-}(t_1, t_2) = 1/2(w_{+-}(t_1, t_2) + w_{-+}(t_1, t_2)) = \sin^2 g(t_2 - t_1)$

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 In the Necker-Zeno model, the probability for state |-> at time t₂ under the condition of state |+> at time t₁ (and vice versa) is:

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- Then $p^-(t_1, t_2)$ for anti-correlated states at t_1 and t_2 is: $p^-(t_1, t_2) = 1/2(w_{+-}(t_1, t_2) + w_{-+}(t_1, t_2)) = \sin^2 g(t_2 - t_1)$
- For $\tau := t_3 t_2 = t_2 t_1$, Bell's inequality turns into the sublinearity condition $p^{-}(2\tau) < 2p^{-}(\tau),$

maximally violated for $g\tau = \pi/6~(\sin^2 g \, 2\tau = 3/4, \, \sin^2 g \, \tau = 1/4).$

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- For t₀ = 1/g ≈ 300 ms we obtain τ = π/6 ⋅ t₀ ≈ 157 ms as the optimal time difference between measurements of s(t_i).
- Problem: measurements must be as non-invasive as possible to establish a significant violation of Bell's inequality.

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Appended Material

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- Observables A ∈ A are (identifyable with) mappings A : Z → Z which associate to every state z ∈ Z another state A(z).
- To every observable A belongs a set *specA* of possible outcomes of an evaluation (e.g., "measurement") of A.
- With A and B, also A \circ B is an observable. (An addition of observables is not defined.)
- There is a unit observable 1, $spec 1 = {true}$, such that: $1A = A1 \quad \forall A \in A$.
- For a zero state o and a zero observable O, $specO = \{false\}$, we have: $A(o) = o, AO = OA = O, \forall A \in A,$ $O(z) = o \forall z \in Z.$
- Observables *P* with *specP* = {true, false} are propositions with the operations negation, conjunction, adjunction as usual.

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 A has the structure of a monoid, generally non-commutative. The non-commutative case implies the concepts of: complementarity (incompatibility) of observables, dispersive states; entanglement (holistic correlations) among observables. (Cf. partially Boolean algebra of propositions.)

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- The axiomatic framework of generalized QT does not prescribe the decomposition of a system Σ into subsystems. In particular there is no tensor product construction for composite systems.
- For the dynamical evolution of Σ one may assume a one-parameter (semi-) group of endomorphisms. However, there is no prescribed kind of dynamical evolution for subsystems of Σ and their interaction.

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"Most generalized" QT does not use key features of ordinary QT

